EWD-L-MSTJ4

User's Guide

(V1. 0)

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Note: the system is applicable to "moving car" elevators. Please read the following sections carefully before using. **Notice:** in any case, we are only responsible for the quality of the products within the warranty period.

Statement: due to technological progress, the company reserves the right to change the product; For the technical parameters, please refer to the random product manual.

System overview

-. "EWD-L-MSTJ4"The main features of the weighing device:

1. When the product is working normally, the internal payload of the cage can be directly displayed. The self-study process is simple to operate.

2. Intelligent programming and control process, according to different customer needs, can adjust the percentage of load corresponding to any of the 4-way switch signals output by the controller and the output of turn-off/turn-off, and modify the output mode of analog quantities.

3. Intelligent sensor: choose high-precision xcl-yl-c tension sensor to directly detect the change of load of the car;

4. Wide measurement range (the payload can be set manually according to the demand), high positioning accuracy and intelligent temperature compensation.

5. The electrical performance conforms to the standard requirements of "international electrotechnical commission (IEC)";

6. The core is composed of a high-precision load sensor and a high-performance monolithic microcomputer.All working parameters can be set on site.

7. Output full-load and overload signals directly according to the change of cage payload;.

8. With the ability of manual fine-tuning correction of working parameters, the error of elevator after decoration can be manually corrected to achieve the purpose of accurate measurement.

9. Unique sensor + controller design structure, simple wiring.

10. From the perspective of the user, it is easy to install and debug, reduce the additional cost in the user's use, and the performance price is higher.

二. "EWD-L-MSTJ4"working principle:

With the development of elevator technology, the influence of elevator weighing device on its performance cannot be ignored. The elevator is in urgent need of high precision, high reliability and multifunction of weighing device. With the continuous development of sensor technology and microcomputer, a high-precision c-type 25Kg sensor is used to detect the electrical signals generated by the elevator cage due to the change of load. High precision sensor: serial communication technology is used to transmit the sensor in a high precision and long distance. The sensor is equipped with 8m signal transmission cable; At the same time, the single chip microcomputer in the controller is used to carry out scientific calculation and processing, and the final accurate direct display of the cage payload in the controller digital hang, realizing the working function of weighing the elevator cage payload. Controller and load sensor Appearance :

Ξ. Controller, sensor, display (optional) appearance: 1.Elevator load weighting device"EWD-L-MSTJ4"Controller



Model	Display
XCL-YL-C appearance of sensor	Directly connected sensor with built-in cable length of 10m by default

2.High precision C sensor

Model		Display	
Display			
	Brown	DC24V+	
Qualification	Blue	com	
definition	Black	Signal +	Wire Length 6m
	Gray	Signal -	

3.LED large-screen display (optional)

- 四. Controller interface diagram and description:
 - 1. Controller interface diagram:



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2.Controller port details:

			Function	Explanation		
		1	J1Relay COM port	With the P2 to produce effective logic	Function : Be	
	Switching	2	-	system default"J1": 5Kg No load Dynamic open output	programmed as"J1 \sim J4"(No load - over load)output signals to	
PJ		3	J2、J3、J4 Relay com port	With P4.P5.P6, to produce effective logic	participate in elevator	
		4		system default"J2": Light load Dyn. Close output	logic control.	
		5		system default"J3": Related load Dyn close output;	2.Max loading Capacity: DC/AC 48V/500mA	
		6	J4 Relay Output	system default"J4": Overload Dyn,open output;		
	Lock 1		Lock signal COM port			
PM		2	DC+24V lock signal, Can access the door lock signal and brake signal		polarity when connecting	
РХ	Anal og	3	0~10V;10~0V;Analog voltage output	Used for pre-torque compensation of the drive sy	stem	
		4	COM Connect the governor to the analog common			
PV	Power suppl	у	System power supply port:	AC/DC 24V / 200mA		
PG	Sensor connection port	P G 1	EWD-L-MSTJ4 controller, c	contact XCL-YL-C sensor		
SW	toggle switch		Toggle switch for system debugging			

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Ī	Displ	External	Port access black and gray signal line,Power supply: DC+24V/1A
l	ay	monitor	
		connection	
		port	

①It is absolutely impossible to connect the output port other than the "PV" device directly to the external power supply, which may cause permanent damage.

(Note:PX and PM port with Polarity requirements and voltage rating requirements)

Ξ 、Controller Dimensions:



Installation and debugging

 $\dot{\boldsymbol{\mathcal{T}}}_{\boldsymbol{\mathcal{T}}}$ XCL-YL-C sensor dimension drawing and installation position diagram and installation notice

1. Sensor size drawing:





2. Installation:



Note:The green part is the welding accessories: 2 pieces in total, 2 welding points after each piece;The user can weld the welding accessories with the bearing beam by electric welding

3. Precautions for controller and sensor installation:

1. The controller should be installed in the control box on the top of the car, preferably not close to the electric control system transformer, governor and other equipment of the elevator. In any case, the sensor and controller should be installed away from the heat source.

"C" type sensor the sensor is installed on the top of the load-bearing beam, and the connection between the sensor and the controller should not be in the same wiring slot as the 110V, 220V and other power sources.
 Connect the sensor wiring port to the PG port of the controller, and at the same time, PV can access the power line according to the system requirements. Be sure to pay attention to the voltage level;

4. When the system is powered on after the check is correct, the controller should display the corresponding working mode.

\pm 、Button Function and Instruction Parameter Code Meaning Description :

1.Button Meaning and Function Description:

No.	Button icon Function		Explanation	
1	1 Set and confirm Button (SET)		Set a parameter and confirm the internal data function	
2	Switch / cursor shift Button(SHIFT)		Used to switch the digital display digit	
3	[▼]	Data increase Button (ADD)	Change the internal value of the parameter	

2.Button to use method description:

(1)Set and confirm button [\blacksquare] Instructions:

When power is displayed, press it [■], Enter the parameter setting status, by [⊃] and [▼] button Enter the setting parameter, Can be set accordingly. Finish setting, press [■] button check, Save the parameters.

(2)Switch / cursor shift buttons [**?**] Instructions:

In the parameter setting state, press once $[\mathcal{P}]$, The cursor moves one by one, to the last one, Press the toggle / cursor shift button $[\mathcal{P}]$ And cycle back to the first place.

(3)Data increase button 【▼】Instructions:

In the parameter setting state, press once (V), Add one to the cursor bit data, add the maximum value of the set data and then cycle back to the minimum value of the data.

3. With the decimal point of the parameters of the process of adjusting the use of key examples:

After powering on the product, press $[\]$ button to enter the instruction setting state. When "00000" is displayed, press $[\]$ button to move the flashing cursor to the last digital tube. Press $[\]$ key to adjust the digital display to "00001", press $[\]$ button to enter the command parameter setting state, digital display "dd - c", press $[\]$ buttons to enter this Parameter modification mode, display "00001" means that the decimal point is 1 bit. Press $[\]$ and $[\]$ to change the digital tube display to "00002", press $[\]$ key to confirm this parameter is modified, the digital tube decimal point will move one by one. (Note: other instruction item parameters can be modified and confirmed in accordance with this method.)

3.Instruction Parameter Code Meaning Description:

No	Instruction parameter code	Function code	Code default data	Function and explanation
1	00001	ddc	00001	Display the decimal point position setting, the factory default for the 1-bit display "00001", adjustable 4 decimal point adjustment
2	00002	Lc01	1000.0	The amount of load range set, according to the different capacity of the elevator directly to the manual set to the load range can be.
		Bj1	0005.0	J1 for the no-load signal output corresponding to the car load, the default setting elevator car load 5.0kg: (adjustable range of 0 ~ 15Kg)
		Вј2	0005.0	J2 for the light load signal output corresponding percentage, the default setting for the amount of 5% output action, adjustable range of 0% to 150%
3	00003	BJ3	0090.0	J3 for the full load signal output corresponding percentage, the default setting for the amount of 90%, the percentage can be adjusted from 0% to 150%
-		BJ4	0105.0	J4 for the overload signal output corresponding percentage, the default setting for the amount of 105%, the percentage can be adjusted from 0% to 150%
4	00004	BJ-HL	BJ1-L	J1 relay dynamic output, dynamic (L) / moving (H) adjustable

			BJ2-H	J2 relay moving output, moving off (L) / moving together(H)adjustable
			BJ3-H	J3 relay moving output, dynamic (L) / moving (H) adjustable
			BJ4-L	J4 relay dynamic output, dynamic (L) / moving (H) adjustable
			Da-00	Analog output mode corresponds to P9 ~ P10 terminal port output 0 ~ 10V
5	00005	Dac	Da-01	Analog output mode corresponds to P9 ~ P10 terminal port output 10 ~ 0V
6	00006	HELP-	01	Restore factory settings
7	00007	B2c	B2-01	Multiplier parameter setting, multiplied by the amount of 1 times, "01 ~ 99" value corresponding to the amount of 1 to 99 times the amount of adjustable; ★ multiplier parameters to be modified after the completion of self-learning after the completion of confirmation
		L-H-2	LL1	The controller learns the no load parameter;
8	00008		HH1	The controller self - learns the load parameter
9	00009	l-h-2	1000.0	Fine-tuning the coefficient setting to fine-tune the learning results

八、System debugging methods and instructions (self-learning):

(Here to lift the amount of 1000Kg as an example to describe the load range setting and "no load and the amount of two self-learning" process)

Before the system debugging:

①.Products must be in strict accordance with the "EWD-L-MSTJ4 user manual" for self-learning, otherwise it will cause the product can not be used and product measurement accuracy is not accurate.

2.Before commissioning, it is necessary to specify the weight of the car. The weight of the truck can not exceed the total range of the

sensor. Otherwise, the sensor will be damaged and the product will not be used.

1. Elevator load range setting:

Note: ①1. Product digital tube display the default decimal point to 1, the unit is Kg, For example :the case shows "1000.0", that is,1000kg.



2. Attention:

① product no-load self-learning before the car must ensure that there is no load and debris, otherwise it will lead to a greater error in the weighing effect.

(2) product no-load - the two-point self-learning process, must be "LL-01" first study no-load, "HH - 1" retraining, otherwise it will lead to the product can not be used.



EWD-L-MSTJ4 Series of intelligent elevator weighing device technical documents of the [user manual] **3.Lift the amount of self-learning process**:



九、Multiplication parameter setting process description (auxiliary function):

Note: Repeated parameter debugging must be in the product after the completion of Chapter 8 product self-learning process before they take effect. Multiplier parameter adjustment range of " $01 \sim 99$ ", that is, the product multiplier for the amount of 1 to 99 times the amount for customers to choose. The product default multiplier parameter value is 1 times the amount of time to restore the factory settings after the product multiplier parameters are restored to the product default multiplier parameter value of the rated load of 1

times.

1. Multiply parameter setting process:

When the system is displayed normally, Press $[\square]$ to enter the instruction selection state, and when "00000" is displayed; press $[\square]$ and $[\square]$ button to change the digital tube display to "00007". "Press $[\square]$ key to display "bz - c", press the $[\square]$ key again to enter the command parameter to modify the state, the product digital hanging display "bz-01" (after the two digital display "01" That is doubled.

2.For Example:

Has completed the amount of 1000kg self-learning process of the product, into the normal working condition. At this time digital tube Display "1000.0" for the current car payload value of 1000kg.

According to the above parameter setting process will be multiplied parameter value is set to "bz-05", and successfully saved 5 times Parameter value. At this point the product light load action load value from the original 1000kg *5% = 50kg also doubled, this When the product in the 1000kg *5 * 5% = 250kg output light load switch signal. And so on, the load signal and The load value of the overload signal is also increased by 5 times. The output of the product will also be based on the load of the elevator, Corresponding to 5 times the value of the analog output changes.

System Features

+	Technical Specif	ications:
1	Application	Suitable for the use of movable car/fixed car bottom elevator.
2	Floor Compensation	Artificial changes in learning errors and fine-tuning
3	Sensitivity	Elevator Rated Capacity/1000kg(Example: The rated capacity is 1000 $\rm kg$, and the sensitivity is 1 $\rm kg$) [This data may be affected by elevator mechanical performance)
4	System Error	≤0.25%(5~40°C)
5	Non-Linearity	≤0.25%
6	Ambient Temperature	-20∼55℃
7	Relative Humidity	20%~90%RH
8	Reaction Time	≤0.25 seconds

9	Output Mode	Programmable 4-way switch signal	 ①4-channel programmable output modes are: No load, light load,rated load, overload (customer may set the changing range freely) ②Each channel can be programmed as dynamic Close or Open contact ③Contact Capacity: DC/AC 48V/100mA Full compensation range 0~10V;10~0V 			
10	Power supply	AC/DC24(±10%)V / 200mA				
11	Installation Place	Load sensor :Above the bearing beam Controller :control Cabinet in machine room				
12	Overall Size	Controller parts: 115×90×40 mm3				

Note: Use of strength exceeding the limit parameters listed above may result in abnormal system operation or permanent damage.

Promise

seal will not be dealt with).

 $(2)\mbox{For any requirement of special functions, make it out by mail.}$

(3)Any system abnormality in adjustment or operation, please contact our company directly.

<u>Other</u>

Packing list:	EWD-L-MSTJ4 Controller	1set
	Ф4×20mm Fastening Screw sets	4sets
	User's Guide	1pcs
	Sensors	1pcs