EWD-L-BMSJ4

Villa Elevator User's Guide

(V2.0)

Xi'an Excellent Electromechnical Co., Ltd

-, "EWD-L-MSJ4"The main functions and characteristics of the weighing device **P**3 □ . "EWD-L-MSJ4"Installing Method and Working Principle Product Overview P4 Ξ_{\sim} Product Appearance and Type Nomination **P6** Controller interface diagram and description **P8** π Controller dimensions **P9** 六、Sensor dimensions and installation location diagram and installation precautions P10 \pm 、Button function and instruction code meaning explanation P14 八、System debugging methods and instructions Installation & (self-learning) Adjustment 1. Elevator Rated load rang setting P15 P16 2.No-load self-study mode of work 3. The amount of self-learning work mode P17 P18 九、Multiplier parameter setting and description (auxiliary function) P19 +, Technical Specifications System Characteristics Promise P20 Other **P20**

EWD-L-BMSJ4 intelligent elevator weighing device technical documents [user manual V2.0]

Note: Under any condition, our part is just responsible for the quality of product in the period of guarantee service.

Declaration: For the reason of technology advancement, our company reserves the right of improving product. As for the relevant technical parameters, Please refer to the technical handbook delivered with the product.

System Overview

—. "EWD-L-BMSJ4"The main features of the weighing device:

1. The normal work of the product, the direct display of the car internal payload, self-learning process is simple.

2. Intelligent programming and control process, according to different customer needs, the controller output of the 4-way switch signal in any one of the signal corresponding to the percentage of load and dynamic / dynamic output adjustment, and the output simulation The amount of the way to modify.

3. Intelligent sensor equipment: the use of high-precision XKL-5FM-
Kn load intelligent sensor, direct detection of car load changes;

4. Wide measurement range (payload can be manually set according to demand), high positioning accuracy, intelligent temperature compensation.

5. Electrical performance in line with the "International Electrotechnical Commission (IEC)" standard requirements;

6. The core uses high precision load cell and high performance single chip microcomputer. Can set all the working parameters.

7. Unique programmable output signal control mode, suitable for a variety of activities of the car to mention the elevator weighing signal on the demand.

8. With the working parameters of artificial fine-tuning correction ability, the elevator can be modified after the artificial correction, so as to achieve the purpose of accurate measurement.

9. Unique sensor + controller design structure, wiring is simple.

10. Everything from the user point of view, easy to install, easy to debug, reduce the use of additional costs, performance and high cost.

__. "EWD-L-BMSJ4"working principle:

With the continuous progress of elevator technology, elevator weighing device on its performance has been to the point where it can not be ignored. Elevator on the weighing device of high precision, high reliability, multi-functional needs are imminent. In the sensor technology and micro-computer continues to develop today, the use of high-precision XKL-5FM rubber sensor to detect the elevator car due to load changes caused by electrical signals. High precision XKL-5FM rubber sensor: the use of serial communication technology for its long-distance high-precision non-destructive transmission; sensor comes with 8 ~ 10m signal transmission cable; at the same time using the microcontroller microcontroller to its scientific computing, the final precision Directly in the controller digital display shows the car inside the payload, to achieve the elevator car payload weighing work function.

 \equiv . Controller and load sensor Appearance :



2. High precision XKL-5FM-aKn load sensor

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3. 传感器选型及外观尺寸

Load Sensor						
Model	XYL-5H (OR EWD-A34)	XYL-5H/5018 -15KN	CL-YB-25/1. 2T	EWD-25E	steel belt load sensor	XYL-2/M
External dimensio n	See attached	See attached	See attached	See attached	See attached	See attached

四. Controller interface diagram and description: 1.Controller interface diagram



2.Controller port details:

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			Function	Explanation	
		1	J1Relay COM port	With the P2 to produce effective logic	1. Function : Be
	Switching	N()	J1 Relay Output	system default"J1": 5Kg No load Dynamic open output;	programmed as"J1 \sim J4"(No load - over load)output signals to participate in
ΡJ		3	com port	With P4.P5.P6, to produce effective logic	elevator logic control
		4	J2 Relay Output	system default"J2": Light load Dyn. Close output	2.Max loading Capacity: DC/AC 48V/500mA
		5	J3 Relay Output	system default"J3": Related load Dyn close output;	
		6	J4 Relay Output	system default"J4" : Overload Dyn,open output;	
РМ	Lock	1	Lock signal COM prot	Note the voltage difference and the cor	nection polarity when
		2	DC+24V lock signal, Can access the door lock signal and brake signal		
PX	Anal og	3	0~10V;10~ 0V;Analog voltage output	Used for pre-torque compensation of the dri	ve system
		4	COMConnect the governor to the analog common		
PV	Power supp	ly		System power supply port: AC/DC 24V / 2	200mA

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	Sensor connection	PG1PG2P G3PG4PG	
	port	5PG6	EWD-L-MSJ4 controller , 4 sensors or 6 sensors can be used as needed.

①It is absolutely impossible to connect the output port other than the "PV" device directly to the external power supply, which may cause permanent damage.(Note:PX and PM port with Polarity requirements and voltage rating requirements)

<u>T</u>. Size of Controller.





2. Precautions for controller and sensor installation:

1. The controller part should be installed in the control box on the top of the car, and it is best not to be close to the transformer, governor and other equipment of the elevator electric control system. In any case, the sensor and controller should be installed away from the heat source; 2.4 sensors or 6 sensors should be installed on the bottom of the car and connected to the controller. It is better not to be in the same wiring groove with power sources such as 110V and 220V.

3. Connect the sensor connection port to the PG port of the controller, and connect PV to the power cord according to system requirements.

After making sure that the system is energized, the controller should display the corresponding working mode

4.After making sure that the system is energized, the controller should display the corresponding

working mode

Installation and adjustment

六. Sensor dimensions and installation location diagram and installation precautions:

1.Sensor installation location diagram and dimension map: (sensor default installation of four, according to the car weight and rated load increased to 6 sensors)

Size of Load sensor XKL-5FM-DKn





\dot{r} . Button Function and Instruction Parameter Code Meaning Description:

Note: (1) .Press the button, the meaning is to press the button to release.

(2) hold down the button, meaning that the button is pressed for a long time as required.

1. Button Meaning and Function Description:

No.	Button icon	Function	Explanation
1	[=]	Set and confirm Button (SET)	Set a parameter and confirm the internal data function
2	Button(SHIFT)		Used to switch the digital display digit
3			Change the internal value of the parameter

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2.Button to use method description:

(1)Set and confirm button [] Instructions:

When power is displayed, press it $[\bullet]$, Enter the parameter setting status, by $[\supseteq]$ and $[\lor]$ button Enter the setting parameter, Can be set accordingly. Finish setting, press $[\bullet]$ button check, Save the parameters.

(2)Switch / cursor shift buttons [] Instructions:

In the parameter setting state, press once [\Im], The cursor moves one by one, to the last one, Press the toggle / cursor shift button [\Im] And cycle back to the first place.

In the parameter setting state, press once [∇], Add one to the cursor bit data, add the maximum value of the set data and then cycle back to the minimum value of the data.

3. With the decimal point of the parameters of the process of adjusting the use of key examples:

After powering on the product, press $[\bullet]$ button to enter the instruction setting state. When "00000" is displayed, press $[\Rightarrow]$ button to move the flashing cursor to the last digital tube. Press $[\bullet]$ key to adjust the digital display to "00001", press $[\bullet]$ button to enter the command parameter setting state, digital display "dd - c", press $[\bullet]$ buttons to enter this Parameter modification mode, display "00001" means that the decimal point is 1 bit. Press $[\Rightarrow]$ and $[\bullet]$ to change the digital tube display to "00002", press $[\bullet]$ key to confirm this parameter is modified, the digital tube decimal point will move one by one. (Note: other instruction item parameters can be modified and confirmed in accordance with this method.)

3.Instruction Parameter Code Meaning Description:

No	Instruction parameter code	Function code	Code default data	Function and explanation
1	00001	ddc	00001	Display the decimal point position

				setting, the factory default for the 1-bit display "00001", adjustable 4 decimal point adjustment
2	00002	Lc01	1000.0	The amount of load range set, according to the different capacity of the elevator directly to the manual set to the load range can be。
		Bj1	0005.0	J1 for the no-load signal output corresponding to the car load, the default setting elevator car load 5.0kg: (adjustable range of 0 ~ 15Kg)
		Вј2	0005.0	J2 for the light load signal output corresponding percentage, the default setting for the amount of 5% output action, adjustable range of 0% to 150%
3	00003	BJ3	0090.0	J3 for the full load signal output corresponding percentage, the default setting for the amount of 90%, the percentage can be adjusted from 0% to 150%
		BJ4	0105.0	J4 for the overload signal output corresponding percentage, the

				default setting for the amount of 105%, the percentage can be adjusted from 0% to 150%
			BJ1-L	J1 relay dynamic output, dynamic (L) / moving (H) adjustable
			BJ2-H	J2 relay moving output, moving off (L) / moving together(H)adjustable
4	00004	BJ-HL	BJ3-H	J3 relay moving output, dynamic (L) / moving (H) adjustable
			BJ4-L	J4 relay dynamic output, dynamic (L) / moving (H) adjustable
5	5 00005 Da		Da-00	Analog output mode corresponds to P9 ~ P10 terminal port output 0 ~ 10V,
		24 0	Da-01	Analog output mode corresponds to P9 ~ P10 terminal output 10 ~ 0V,
6	00006	HELP-	01	Restore factory settings

7	00007	B2c	B2-01	Multiplier parameter setting, multiplied by the amount of 1 times, "01 ~ 99" value corresponding to the amount of 1 to 99 times the amount of adjustable; ★ multiplier parameters to be modified after the completion of self-learning after the completion of confirmation
8	00008	8 L-H-2		The controller learns the no load parameter;
			HH1	The controller self - learns the load parameter
9	00009	I-h-2	1000.0	Fine-tuning the coefficient setting to fine-tune the learning results

八、System debugging methods and instructions (self-learning):

(Here to lift the amount of 1000Kg as an example to describe the load range setting and "no load and the amount of two self-learning" process)

EWD-L-BMSJ4 intelligent elevator weighing device technical documents [user manual V2.0] Before the system debugging:

①: Products must be in strict accordance with the "EWD-L-MSJ4 user manual" for self-learning, otherwise it will cause the product can not be used and product measurement accuracy is not accurate.

②: Before commissioning, it is necessary to specify the weight of the car. The weight of the truck can not exceed the total range of the sensor. Otherwise, the sensor will be damaged and the product will not be used.

1.Elevation range setting: Note: ①1. Product digital tube display the default decimal point to 1, the unit is Kg, For example :the case shows "1000.0", that is,

2.1000kg.



Note:

 product no-load self-learning before the car must ensure that there is no load and debris, otherwise it will lead to a greater error in the weighing effect.
 product no-load - the two-point self-learning process, must be "LL-01" first study no-load, "HH - 1" retraining, otherwise it will lead to the product can not be used



3.Lift the amount of self-learning process:



- 九、Multiplication parameter setting process description (auxiliary function)):
 - Note : Repeated parameter debugging must be in the product after the completion of Chapter 8 product self-learning process before they take effect. Multiplier parameter adjustment range of "01 ~ 99", that is, the product multiplier for the amount of 1 to 99 times the amount for customers to choose. The product default multiplier parameter value is 1 times the amount of time to restore the factory settings after the product multiplier parameters are restored to the product default multiplier parameter value of the rated load of 1 times.

1. Multiply parameter setting process:

When the system is displayed normally, Press $[\square]$ to enter the instruction selection state, and when "00000" is displayed; press $[\square]$ and $[\nabla]$ button to change the digital tube display to "00007". "Press $[\square]$ key to display "bz - c", press the $[\square]$ key again to enter the command parameter to modify the state, the product digital hanging display "bz-01" (after the two digital display "01" That is doubled, for example

2. for example:

Has completed the amount of 1000kg self-learning process of the product, into the normal working condition. At this time digital tube

Display "1000.0" for the current car payload value of 1000kg.

According to the above parameter setting process will be multiplied parameter value is set to "bz-05", and successfully saved 5 times

Parameter value. At this point the product light load action load value from the original 1000 kg * 5% = 50 kg also doubled, this

When the product in the 1000kg * 5 * 5% = 250kg output light load switch signal. And so on, the load signal and

The load value of the overload signal is also increased by 5 times. The output of the product will also be based on the load of the elevator

Corresponding to 5 times the value of the analog output changes.

System Features

+、Technical Specifications:

1	Application:	eing applicable to all fixed car platform elevators		
2		Artificial changes in learning errors and fine-tuning.		
	Compensation			
3	Sensitivity:	Elevator Rated Capacit/1000 (Example: The rated capacity is 1000 $ m kg$,		
		and the sensitivity is 1 $ m kg$) [This data may be affected by elevator mechanical		
		performance.]		

T				
4.	System	≤0.25%(5∼40° C)		
	Error:			
5.	Non-Linearity:	≤0.25%		
7.	Output Mode:	Programmable 4-way switch signal:	 ①4-channel programmable output modes are: No load, light load, rated load, overload (customer may set the changing range freely). ②Each channel can be programmed as dynamic Close or Open contact. ③Contact Capacity: DC/AC 48V/100mA。 	
		Linear analogue:	Full compensation range 0~10V;10~0V	
8.	Ambient Temperature:	: -20∼55℃		
9.	Relative Humidity:	20%~90%RH		
10.	Reaction Time:	≤0.25 秒		
11.	Power supply:	AC/DC24(±10%)V / 200mA		
12.	nstallation Place:	Load sensor: under movable car platform。 Controller: Control Cabinet in machineroom		
13.	Overall Size:	Controller parts: 115×90)×40 mm ³	

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: The intension exceeding the limit parameters listed above may result in the abnormality or permanent damage to the system.

Promise

(1)If this system appears any quality problem of product itself in 1 year after delivery, it will be replaced freely (damage of the product seal will not be dealt with) 。

(2)For any requirement of special functions, make it out by mail.

(3)Any system abnormality in adjustment or operation, please contact our company directly.

<u>Other</u>

1. Packing list:	EWD-L-MSJ4 Controller	1se	et	
not.	Φ4×40mm <i>Fastening Screw sets</i> Load sensor XKL-5FM-□Kn User's Guide	4st 4/6 1	-	ts
2.Address	Xi'an Excellent Electromechnical CoLtd			
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